

# Flexible SON Function Coordination Framework based on Machine Learning

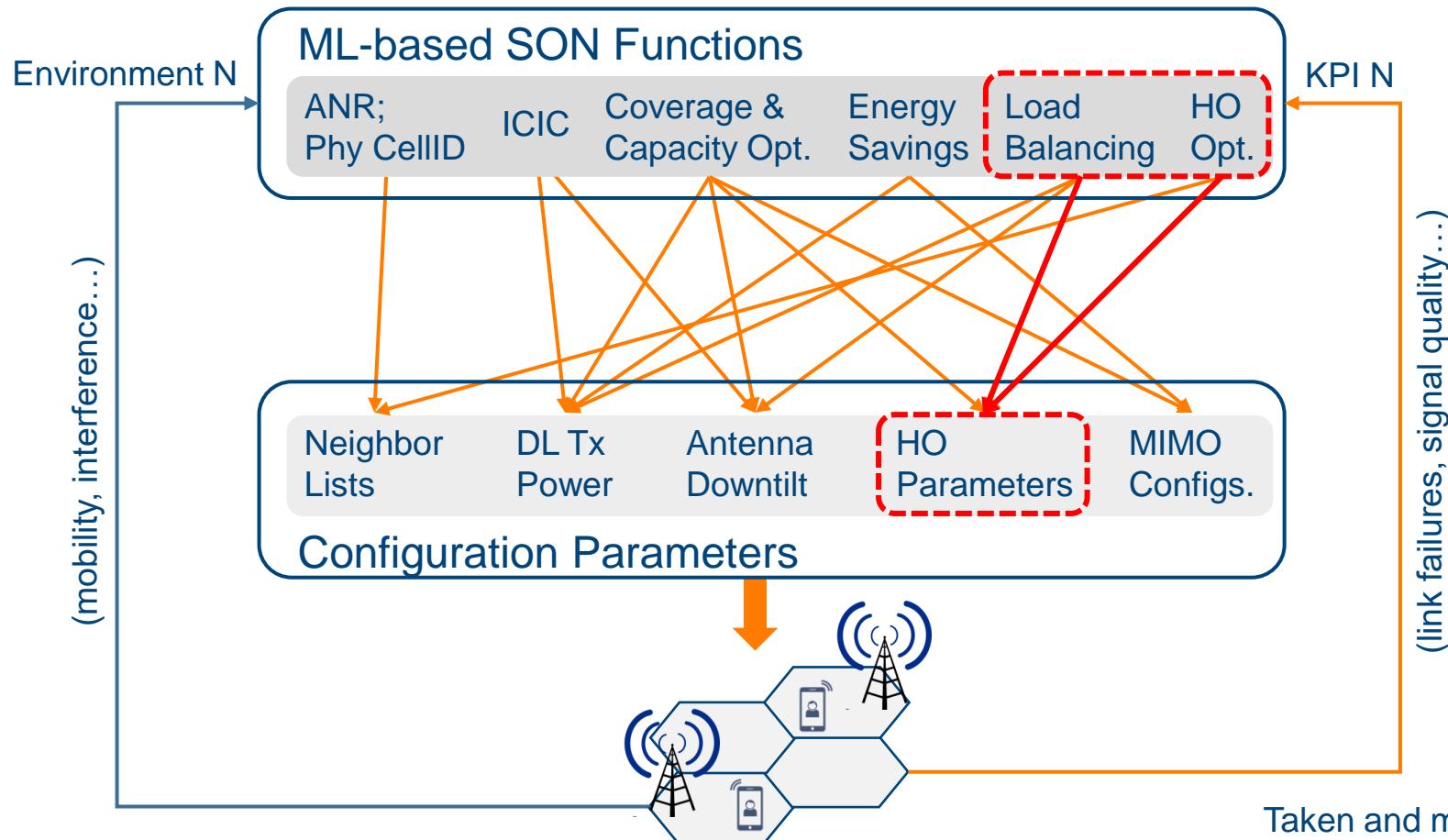
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# Outline

- Problem Formulation
- Motivation
- Implicit Coordination
- Simulation Results
- Conclusions

# Problem Formulation

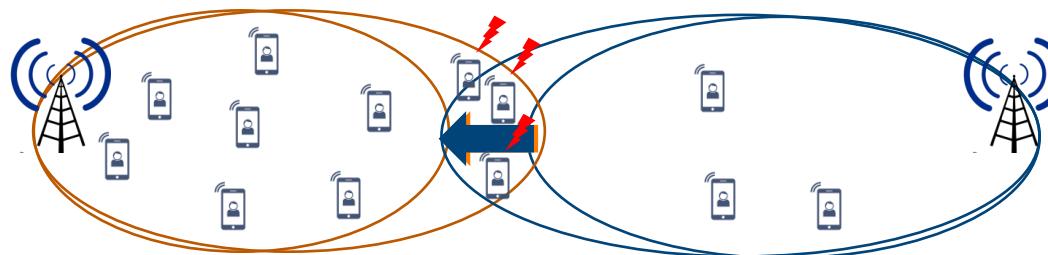
- Complexity of mobile networks increases – automation is needed



# Motivation: Implicit Coordination

- Mobility Robustness Optimization (MRO) – handover (HO) optimization
- Mobility Load Balancing (MLB) – minimizing overload in cells

$$\text{A3 event: } \frac{RSRP_s + Hys + CIO_{s,t} < RSRP_t}{TTT}$$



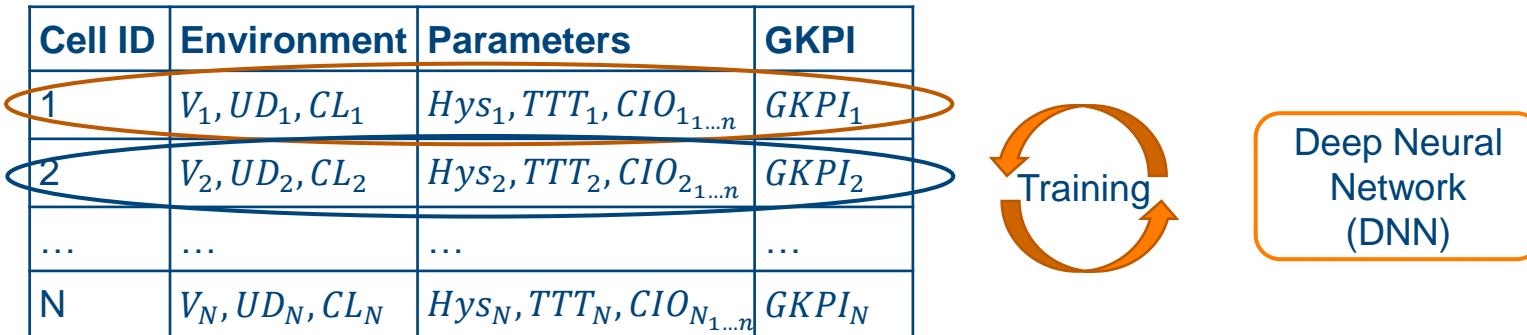
SF	Environment	HO config. Parameters	KPI
MRO	<ul style="list-style-type: none"><li>Velocity</li></ul>	<ul style="list-style-type: none"><li>Hysteresis</li><li>Time To Trigger (TTT)</li></ul>	<ul style="list-style-type: none"><li><math>\text{HOAP} = \frac{0.2*PP + 0.4*RLFL + 0.4*RLFE}{Users_{cell}}</math></li></ul>
MLB	<ul style="list-style-type: none"><li>Users distribution</li><li>Cell load</li></ul>	<ul style="list-style-type: none"><li>Cell Individual Offset (CIO)</li></ul>	<ul style="list-style-type: none"><li># of unsatisfied users (# of UUs)</li></ul>

Minimize GKPI i.e. transferring users from an overloaded cell to neighboring cells while minimizing any HO-related issues for them.

$$GKPI_c = w_1 * HOAP_c + w_2 * UUs_c$$

# Decentralized Implementation

- Regression ML model derivation pipeline



- Genetic Algorithm (GA) based optimization [2] – more than 10M configuration combinations

Fitness function:

$$F_c = \widehat{GKPI}_c + \sum_{\substack{n=1 \\ n \neq c}}^N |\Delta GKPI_n|$$

Penalty for disturbing neighbors

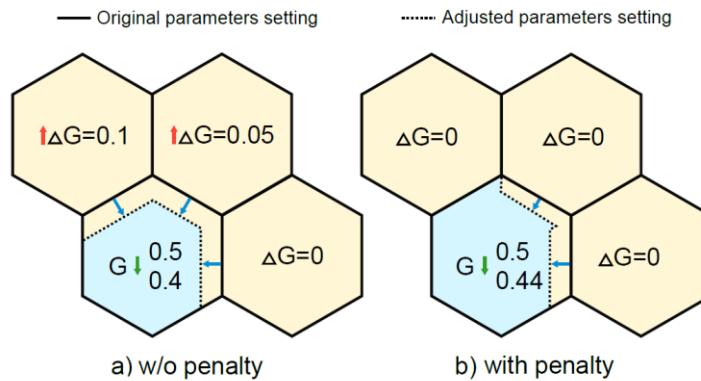
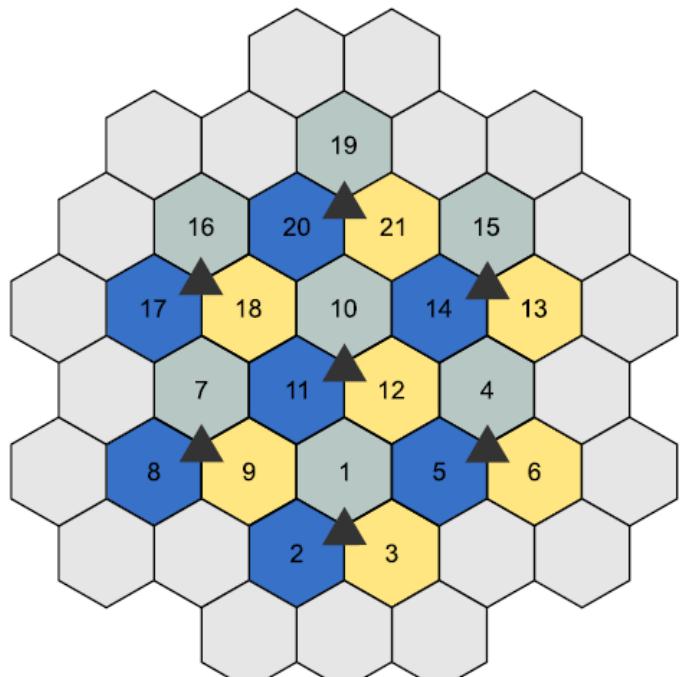
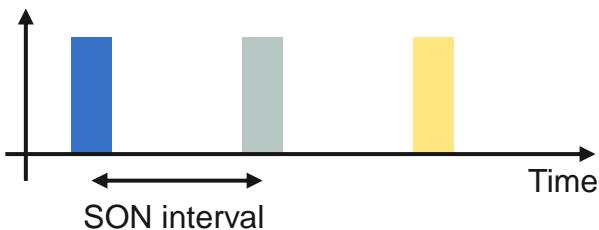


Fig. 1. Applying the two best individuals found using fitness function without a penalization (a) and with a penalization (b).

# Simulation Scenario



Network structure [3]



## Parameters:

- 7 base station with 3 cells
- 420 mobile, 40 static users
- Random walk model
- User's velocity 10-60 Km/h
- SON interval 5 seconds

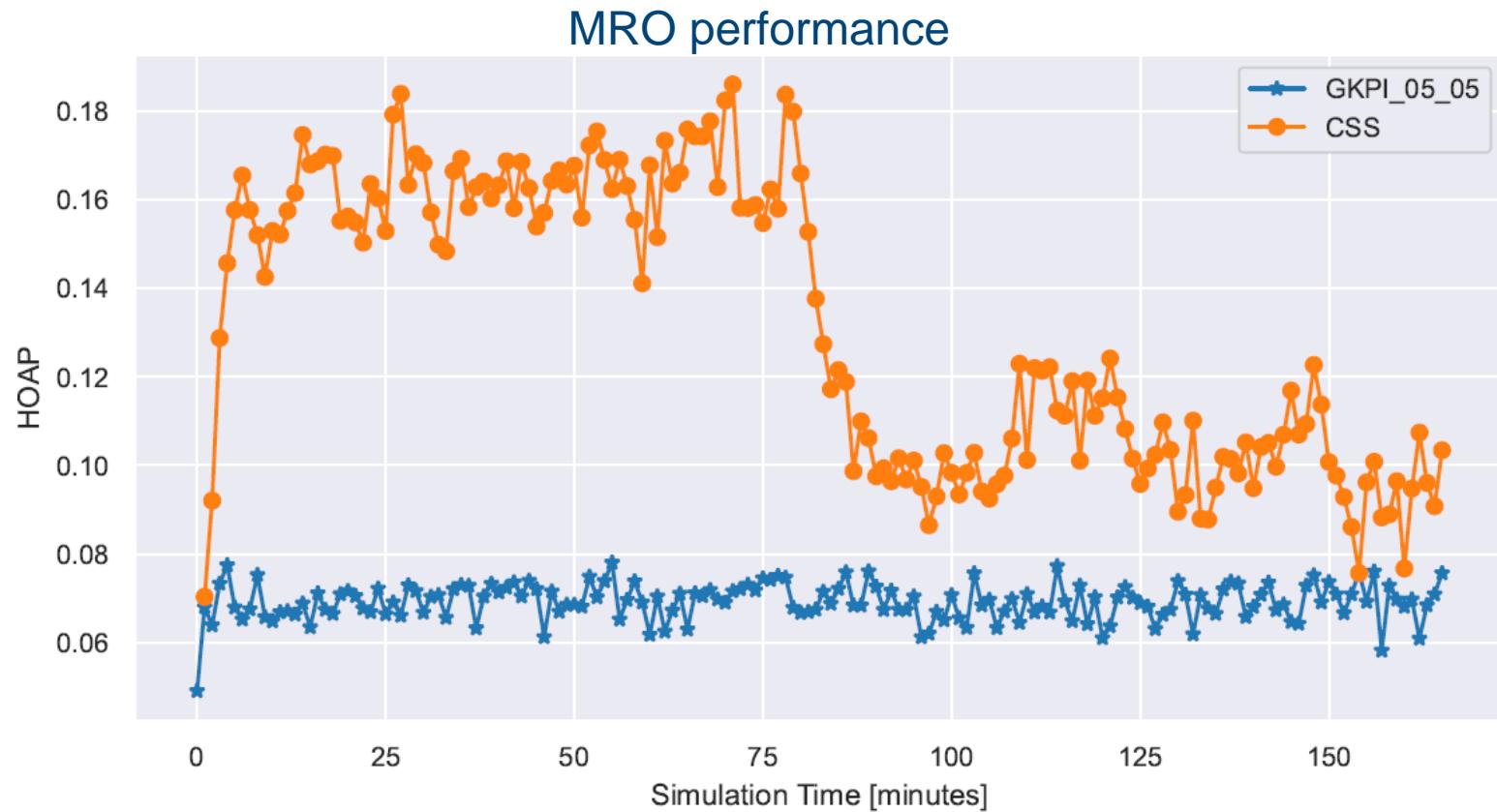
## Benchmark:

- Concurrent Spatial Separation (CSS) – reinforcement learning for MLB and MRO [4]

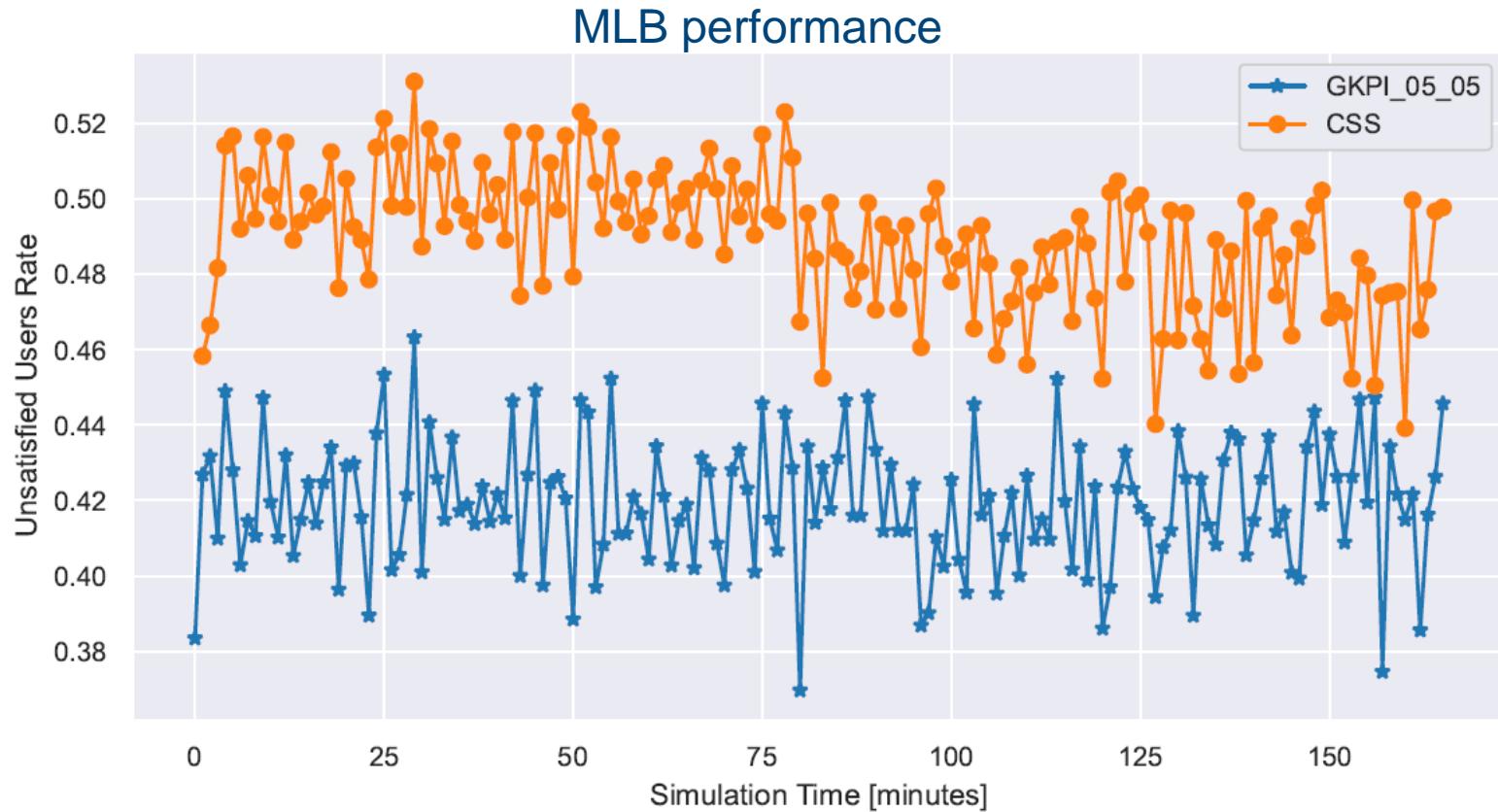
$$\text{GKPI}_c = w_1 * \text{HOAP}_c + w_2 * \text{UUS}_c$$

GKPI Setups	MRO $w_1$	MLB $w_2$
GKPI_05_05	0.5	0.5
GKPI_1_0	1.0	0.0
GKPI_0_1	0.0	1.0

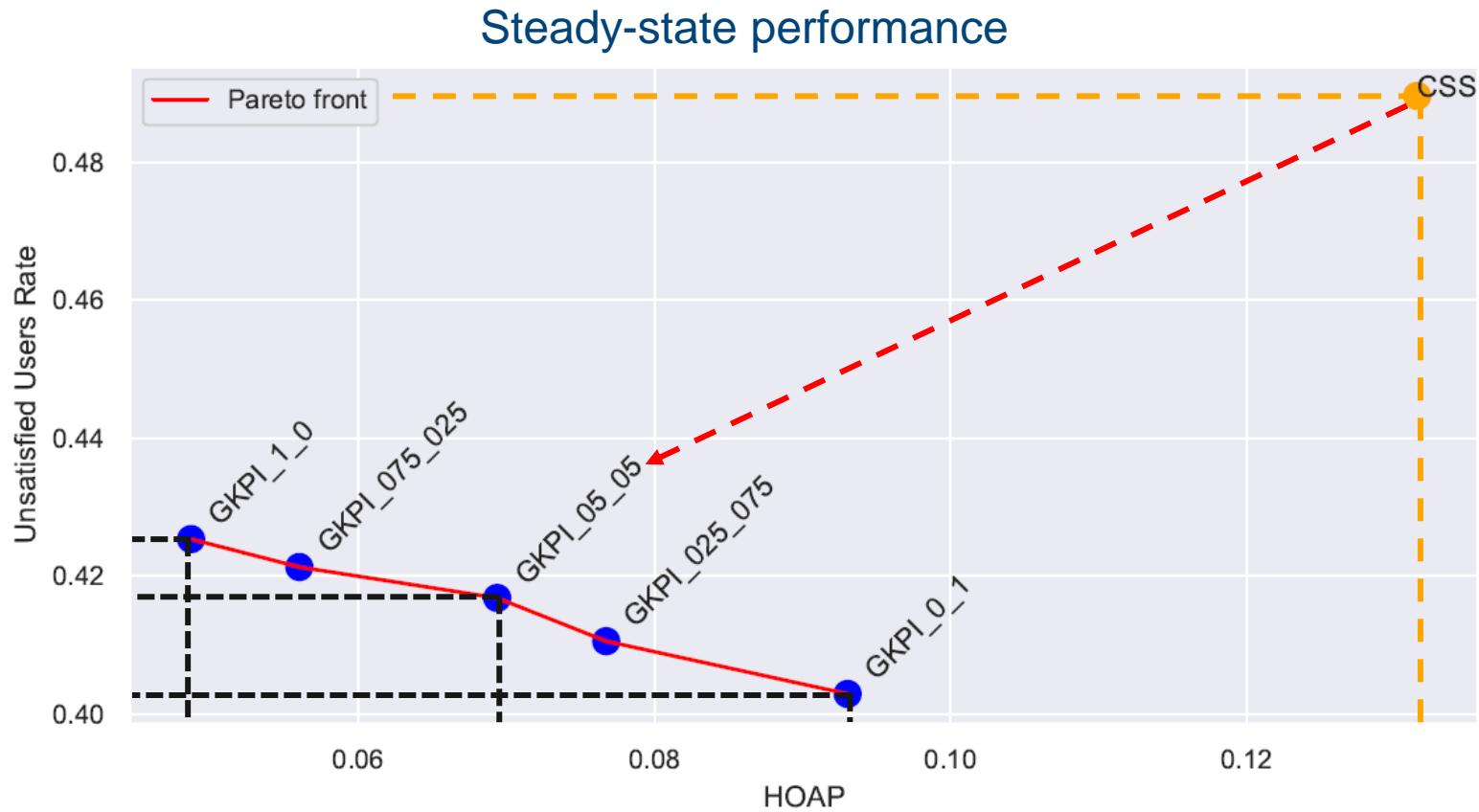
# Simulation Results: MRO



# Simulation Results: MLB



# Simulation Results: Steady-State



# Conclusions

- Proposed an implicit coordination framework (ML + GA), targeting optimization of GKPI
- It employs a decentralized optimization that considers local neighborhood impacts
- Evaluated the framework on the MRO-MLB conflict
- Simulation results showed minimization of the conflict, outperforming the benchmark scheme
- Demonstrated the flexibility of the framework to adapt to different operator needs by varying GKPI weight combinations

# References

1. C. Frenzel, “Objective-driven operations of self-organizing networks,” Ph.D. dissertation, Universit”at Augsburg, 2016.
2. E. Wirsansky, Hands-on genetic algorithms with Python: applying genetic algorithms to solve real-world deep learning and artificial intelligence problems. Packt Publishing Ltd, 2020.
3. J. Sommer and J. Scharf, “IKR simulation library,” in Modeling and Tools for Network Simulation. Springer, 2010, pp. 61–68.
4. S. S. Mwanje and A. Mitschele-Thiel, “STS: space-time scheduling for coordinating self-organization network functions in LTE,” in 2015 IFIP/IEEE International Symposium on Integrated Network Management (IM). IEEE, 2015, pp. 357–362
5. A. Géron, Hands-on machine learning with Scikit-Learn, Keras, and TensorFlow: Concepts, tools, and techniques to build intelligent systems. ” O'Reilly Media, Inc.”, 2019.

# Thank You!



# Back Up Slides

# Parameters

TABLE I  
SIMULATION PARAMETERS

Parameters	Value
Inter-site distance	500 m
Pathloss	$128.1 + 37.6 * \log_{10}[\max(d[\text{km}], 0.035)]$
Shadowing	Standard deviation = 6 dB; Decorrelation distance = 50 m
eNB Tx power	46 dBm
eNB Tx antennas	gain 15 dBi, height = 32 m
Number of users	420 mobile, 40 static (cell 10)
User's velocity	10-60 Km/h
Mobility model	Random Walk
Positions of users	random, uniform distribution
UE receive antennas	gain 2 dBi, height = 1.5m
User data rate	512 kbps
PP Time	5 seconds
T310	0.2s
TTT	0-1280 ms
Hys	0-7 dB steps: 0.2 dBs
Weights in (2)	$w_1 = 0.2$ $w_2 = 0.4$ $w_3 = 0.4$
SON interval	5 seconds
CIO	-6 to + 6 dB steps: 0.5 dBs

TABLE IV  
MODEL'S HYPERPARAMETERS

Model	Hyperparameters	RMSE
DNN	units=58/96/96/1, act=RELU	0.032
XGBoost	n_estimators=167, max_depth=9,	0.044
SVR	C=7.5, gamma=0.05, kernel=RBF	0.053

TABLE III  
GENETIC ALGORITHM PARAMETERS

Parameters	Value
Number of generations	30
Population size	200
Mutation probability	0.1
Crossover probability	0.6
Number of elites	5